

A Riemannian structure on the space of conformal metrics

M. Gursky (Notre Dame)
(joint with J. Streets, UC - Irvine)

Conference on Differential Geometry
In Honor of Claude LeBrun
Centre de Recherches Mathématiques

July 6, 2016

- Main idea: given a conformal class of metrics $[g]$, we want to define a Riemannian metric on this (infinite-dimensional) space.

- Main idea: given a conformal class of metrics $[g]$, we want to define a Riemannian metric on this (infinite-dimensional) space.
- Our metric will be defined for conformal classes on even-dimensional manifolds. Moreover, we will need to restrict to conformal metrics satisfying an 'admissibility' condition.

- Main idea: given a conformal class of metrics $[g]$, we want to define a Riemannian metric on this (infinite-dimensional) space.
- Our metric will be defined for conformal classes on even-dimensional manifolds. Moreover, we will need to restrict to conformal metrics satisfying an 'admissibility' condition.
- Our main focus will be some results in four dimensions, where there are applications to a natural geometric variational problem. In the case of surfaces, it will correspond to the Mabuchi-Donaldson-Semmes metric for the natural Kähler class.

The case of surfaces

- Assume (M, g) is a closed Riemannian surface (of genus $\neq 1$), and let $[g]$ denote the conformal class of g . Define

The case of surfaces

- Assume (M, g) is a closed Riemannian surface (of genus $\neq 1$), and let $[g]$ denote the conformal class of g . Define

$$\mathcal{C}^+ = \{g_u = e^{2u}g \in [g] \mid K_u > 0\},$$

$$\mathcal{C}^- = \{g_u = e^{2u}g \in [g] \mid K_u < 0\}.$$

The case of surfaces

- Assume (M, g) is a closed Riemannian surface (of genus $\neq 1$), and let $[g]$ denote the conformal class of g . Define

$$\mathcal{C}^+ = \{g_u = e^{2u}g \in [g] \mid K_u > 0\},$$

$$\mathcal{C}^- = \{g_u = e^{2u}g \in [g] \mid K_u < 0\}.$$

- Note

$$\mathcal{C}^+ \neq \emptyset \Leftrightarrow \int_M K_g dA_g > 0,$$

$$\mathcal{C}^- \neq \emptyset \Leftrightarrow \int_M K_g dA_g < 0.$$

The inner product

- Note

$$T_u\mathcal{C}^\pm \cong C^\infty(M)$$

i.e., tangent vectors a point (= conformal metric) are just functions.

The inner product

- Note

$$T_u\mathcal{C}^\pm \cong C^\infty(M)$$

i.e., tangent vectors a point (= conformal metric) are just functions.

Definition

For $\alpha, \beta \in T_u\mathcal{C}^+ \cong C^\infty$, we define

$$\langle \alpha, \beta \rangle_u = \int \alpha\beta K_u dA_u$$

and for $\alpha, \beta \in T_u\mathcal{C}^- \cong C^\infty$ we define

$$\langle \alpha, \beta \rangle_u = \int \alpha\beta(-K_u) dA_u$$

The inner product, cont.

- If $g_u = e^{2u}g_0$, then the Gauss curvature and volume forms of g_u and g_0 are related by

$$K_u = e^{-2u}(K_0 - \Delta_0 u), \quad dA_u = e^{2u}dA_0,$$

The inner product, cont.

- If $g_u = e^{2u}g_0$, then the Gauss curvature and volume forms of g_u and g_0 are related by

$$K_u = e^{-2u}(K_0 - \Delta_0 u), \quad dA_u = e^{2u}dA_0,$$

hence we can also express the inner product as

$$\langle \alpha, \beta \rangle_u = \int \alpha \beta (K_0 - \Delta_0 u) dA_0.$$

This is the same as the inner product on the space of volume forms defined by Donaldson ('07).

The inner product, cont.

- If $g_u = e^{2u}g_0$, then the Gauss curvature and volume forms of g_u and g_0 are related by

$$K_u = e^{-2u}(K_0 - \Delta_0 u), \quad dA_u = e^{2u}dA_0,$$

hence we can also express the inner product as

$$\langle \alpha, \beta \rangle_u = \int \alpha \beta (K_0 - \Delta_0 u) dA_0.$$

This is the same as the inner product on the space of volume forms defined by Donaldson ('07).

- To motivate our results in dimension four, we want to point out some geometric properties of $(\mathcal{C}^\pm, \langle \cdot, \cdot \rangle)$, beginning with geodesics.

The geodesic equation

- Let $u : [a, b] \rightarrow \mathcal{C}^+$ be a curve (i.e., $e^{2u}g \in \mathcal{C}^+$). We can use the inner product to define the length of a path:

$$L[u] = \int_a^b \left\| \frac{\partial u}{\partial t} \right\| dt = \int_a^b \left\{ \int_M \left(\frac{\partial u}{\partial t} \right)^2 K_u dA_u \right\}^{1/2} dt.$$

The geodesic equation

- Let $u : [a, b] \rightarrow \mathcal{C}^+$ be a curve (i.e., $e^{2u}g \in \mathcal{C}^+$). We can use the inner product to define the length of a path:

$$L[u] = \int_a^b \left\| \frac{\partial u}{\partial t} \right\| dt = \int_a^b \left\{ \int_M \left(\frac{\partial u}{\partial t} \right)^2 K_u dA_u \right\}^{1/2} dt.$$

- Taking a first variation, we find the geodesic equation:

$$u_{tt} + \frac{|\nabla_u u_t|^2}{K_u} = 0.$$

The geodesic equation

- Let $u : [a, b] \rightarrow \mathcal{C}^+$ be a curve (i.e., $e^{2u}g \in \mathcal{C}^+$). We can use the inner product to define the length of a path:

$$L[u] = \int_a^b \left\| \frac{\partial u}{\partial t} \right\| dt = \int_a^b \left\{ \int_M \left(\frac{\partial u}{\partial t} \right)^2 K_u dA_u \right\}^{1/2} dt.$$

- Taking a first variation, we find the geodesic equation:

$$u_{tt} + \frac{|\nabla_u u_t|^2}{K_u} = 0.$$

- Chen-He ('08) proved partial regularity ($C^{1,1}$) of solutions.

The regularized determinant

- Let

$$F[u] = \int (|\nabla u|^2 + 2Ku) dA - \left(\int K dA \right) \log \int e^{2u} dA.$$

the normalized Liouville energy.

The regularized determinant

- Let

$$F[u] = \int (|\nabla u|^2 + 2Ku) dA - \left(\int K dA \right) \log \int e^{2u} dA.$$

the normalized Liouville energy.

- A metric $g_u = e^{2u}g$ is a critical point of $F \Leftrightarrow$ it has constant Gauss curvature.

The regularized determinant

- Let

$$F[u] = \int (|\nabla u|^2 + 2Ku) dA - \left(\int K dA \right) \log \int e^{2u} dA.$$

the normalized Liouville energy.

- A metric $g_u = e^{2u}g$ is a critical point of $F \Leftrightarrow$ it has constant Gauss curvature.
- Polyakov ('81) showed that if $g_u = e^{2u}g$ have the same area, then

$$\log \frac{\det(-\Delta_u)}{\det(-\Delta_g)} = -\frac{1}{12\pi} F[u].$$

Geodesic convexity

Claim

$F : \mathcal{C}^\pm \rightarrow \mathbb{R}$ is geodesically convex.

Claim

$F : \mathcal{C}^\pm \rightarrow \mathbb{R}$ is geodesically convex.

Proof. Let $u = u(x, t)$ denote a geodesic in \mathcal{C}^+ . Then

$$\frac{d}{dt}F[u] = 2 \int u_t (K_u - \bar{K}_u) dA_u,$$

Geodesic convexity

Claim

$F : \mathcal{C}^\pm \rightarrow \mathbb{R}$ is geodesically convex.

Proof. Let $u = u(x, t)$ denote a geodesic in \mathcal{C}^+ . Then

$$\frac{d}{dt}F[u] = 2 \int u_t (K_u - \bar{K}_u) dA_u,$$

$$\frac{d^2}{dt^2}F[u] = 2\bar{K}_u \left\{ \int \frac{|\nabla u_t|^2}{K_u} dA_u - 2 \left[\int u_t^2 dA_u - \frac{1}{A_u} \left(\int u_t dA_u \right)^2 \right] \right\}.$$

Geodesic convexity

Claim

$F : \mathcal{C}^\pm \rightarrow \mathbb{R}$ is geodesically convex.

Proof. Let $u = u(x, t)$ denote a geodesic in \mathcal{C}^+ . Then

$$\frac{d}{dt} F[u] = 2 \int u_t (K_u - \bar{K}_u) dA_u,$$

$$\frac{d^2}{dt^2} F[u] = 2\bar{K}_u \left\{ \int \frac{|\nabla u_t|^2}{K_u} dA_u - 2 \left[\int u_t^2 dA_u - \frac{1}{A_u} \left(\int u_t dA_u \right)^2 \right] \right\}.$$

To get a sign, we need a kind of “curvature-weighted Poincaré inequality”.

Andrews' inequality

Theorem

(B. Andrews, unpublished) Assume (M, g) has $Ric > 0$.

Andrews' inequality

Theorem

(B. Andrews, unpublished) Assume (M, g) has $Ric > 0$. If $\int \phi dV = 0$, then

$$\frac{n}{n-1} \int \phi^2 dV \leq \int (Ric)^{-1}(\nabla\phi, \nabla\phi) dV,$$

with equality $\Leftrightarrow \phi \equiv 0$ or $(M, g) = (S^n, g_0)$ and ϕ is a first order spherical harmonic.

Andrews' inequality

Theorem

(B. Andrews, unpublished) Assume (M, g) has $Ric > 0$. If $\int \phi dV = 0$, then

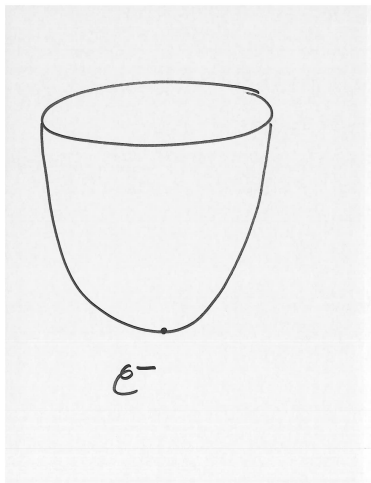
$$\frac{n}{n-1} \int \phi^2 dV \leq \int (Ric)^{-1}(\nabla\phi, \nabla\phi) dV,$$

with equality $\Leftrightarrow \phi \equiv 0$ or $(M, g) = (S^n, g_0)$ and ϕ is a first order spherical harmonic.

- When $n = 2$, $(Ric_u)^{-1} = \frac{1}{K_u} g_u$, and Andrews' inequality applied to $\phi = u_t - \bar{u}_t$ implies $\frac{d^2}{dt^2} F \geq 0$.

Convexity, cont.

- In \mathcal{C}^- , we have strict convexity of F and uniqueness of critical points (i.e., metrics of curvature -1):



Convexity, cont.

- In \mathcal{C}^+ , the Moebius group leads to non-uniqueness (and equality in Andrews' inequality):

Convexity, cont.

- In \mathcal{C}^+ , the Moebius group leads to non-uniqueness (and equality in Andrews' inequality): Let $\sigma : S^2 \setminus \{N\} \rightarrow \mathbb{R}^2$ denote the stereographic projection map, where $N =$ north pole of S^2 .

Convexity, cont.

- In \mathcal{C}^+ , the Moebius group leads to non-uniqueness (and equality in Andrews' inequality): Let $\sigma : S^2 \setminus \{N\} \rightarrow \mathbb{R}^2$ denote the stereographic projection map, where $N =$ north pole of S^2 . Let $\delta_\alpha : x \mapsto \alpha^{-1}x$ denote dilation on \mathbb{R}^2 , where $\alpha > 0$.

Convexity, cont.

- In \mathcal{C}^+ , the Moebius group leads to non-uniqueness (and equality in Andrews' inequality): Let $\sigma : S^2 \setminus \{N\} \rightarrow \mathbb{R}^2$ denote the stereographic projection map, where $N =$ north pole of S^2 . Let $\delta_\alpha : x \mapsto \alpha^{-1}x$ denote dilation on \mathbb{R}^2 , where $\alpha > 0$. Then

$$\psi_\alpha = \sigma^{-1} \circ \delta_\alpha \circ \sigma : S^2 \rightarrow S^2$$

defines a 1-parameter family of conformal maps:

$$\psi_\alpha^* g_0 = e^{2w_\alpha} g_0.$$

Convexity, cont.

- In \mathcal{C}^+ , the Moebius group leads to non-uniqueness (and equality in Andrews' inequality): Let $\sigma : S^2 \setminus \{N\} \rightarrow \mathbb{R}^2$ denote the stereographic projection map, where $N =$ north pole of S^2 . Let $\delta_\alpha : x \mapsto \alpha^{-1}x$ denote dilation on \mathbb{R}^2 , where $\alpha > 0$. Then

$$\psi_\alpha = \sigma^{-1} \circ \delta_\alpha \circ \sigma : S^2 \rightarrow S^2$$

defines a 1-parameter family of conformal maps:

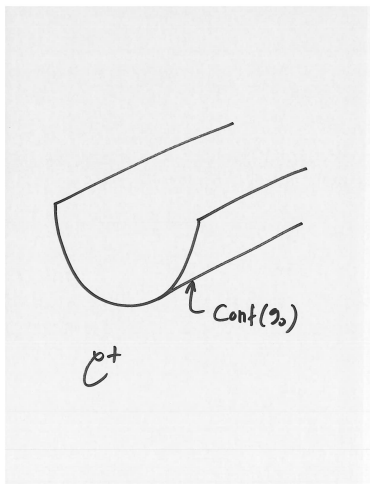
$$\psi_\alpha^* g_0 = e^{2w_\alpha} g_0.$$

Then

$$u(x, t) = w_{e^t}(x)$$

is a geodesic in \mathcal{C}^+ .

Convexity, cont.



Four dimensions

- Schematic description of the inner product in 4-d:

Four dimensions

- Schematic description of the inner product in 4-d:

$$n = 2 : \langle \alpha, \beta \rangle = \int \alpha \beta K dA,$$

$$2\pi\chi(M) = \int K dA,$$

Four dimensions

- Schematic description of the inner product in 4-d:

$$n = 2 : \langle \alpha, \beta \rangle = \int \alpha \beta K dA,$$

$$2\pi\chi(M) = \int K dA,$$

$$n = 4 : 8\pi^2\chi(M) = \int \left(-\frac{1}{2}|Ric|^2 + \frac{1}{6}R^2 \right) dV + \int |W|^2 dV,$$

$$\langle \alpha, \beta \rangle = \frac{1}{4} \int \alpha \beta \left(-\frac{1}{2}|Ric|^2 + \frac{1}{6}R^2 \right) dV.$$

Schouten tensor

- Let $n = 4$, and denote the *Schouten tensor* by

$$A = \frac{1}{2}(\text{Ric} - \frac{1}{6}Rg).$$

- Let $n = 4$, and denote the *Schouten tensor* by

$$A = \frac{1}{2}(\text{Ric} - \frac{1}{6}Rg).$$

- Let $\sigma_2(A) = \sum_{i < j} \lambda_i(A)\lambda_j(A)$, the second symmetric function. Then

Schouten tensor

- Let $n = 4$, and denote the *Schouten tensor* by

$$A = \frac{1}{2}(\text{Ric} - \frac{1}{6}Rg).$$

- Let $\sigma_2(A) = \sum_{i < j} \lambda_i(A)\lambda_j(A)$, the second symmetric function. Then

$$8\pi^2\chi(M) = \int |W|^2 + 4 \int \sigma_2(A)dV,$$

and

$$\langle \alpha, \beta \rangle_g = \int \alpha\beta\sigma_2(A_g)dV_g.$$

Definition.

Let

$$\mathcal{C}^+ = \{g_u = e^{2u}g : \sigma_1(A_u) > 0, \sigma_2(A_u) > 0\},$$

Definition.

Let

$$\mathcal{C}^+ = \{g_u = e^{2u}g : \sigma_1(A_u) > 0, \sigma_2(A_u) > 0\},$$

$$\mathcal{C}^- = \{g_u = e^{2u}g : \sigma_1(A_u) < 0, \sigma_2(A_u) > 0\},$$

Definition.

Let

$$\mathcal{C}^+ = \{g_u = e^{2u}g : \sigma_1(A_u) > 0, \sigma_2(A_u) > 0\},$$

$$\mathcal{C}^- = \{g_u = e^{2u}g : \sigma_1(A_u) < 0, \sigma_2(A_u) > 0\},$$

- Note that

$$\sigma_1(A) = \frac{R}{6},$$

where R is the scalar curvature.

Definition.

Let

$$\mathcal{C}^+ = \{g_u = e^{2u}g : \sigma_1(A_u) > 0, \sigma_2(A_u) > 0\},$$

$$\mathcal{C}^- = \{g_u = e^{2u}g : \sigma_1(A_u) < 0, \sigma_2(A_u) > 0\},$$

- Note that

$$\sigma_1(A) = \frac{R}{6},$$

where R is the scalar curvature.

(For reasons we'll touch on later, we will only consider \mathcal{C}^+ .)

Question: When is $C^+ \neq \emptyset$?

Question: When is $C^+ \neq \emptyset$?

- In analogy with two dimensions, we have

Theorem.

(Chang-G-Yang, '96) If $\int \sigma_2(A) dV > 0$, $R > 0$, then $C^+ \neq \emptyset$.

The σ_k -Yamabe problem

The σ_k -Yamabe problem:(J. Viaclovsky)

Given $[g]$, find $\tilde{g} \in [g]$ such that

$$\sigma_k(A_{\tilde{g}}) = \text{const.}$$

The σ_k -Yamabe problem

The σ_k -Yamabe problem:(J. Viaclovsky)

Given $[g]$, find $\tilde{g} \in [g]$ such that

$$\sigma_k(A_{\tilde{g}}) = \text{const.}$$

- When $k = 1$, this corresponds to the Yamabe problem.

The σ_k -Yamabe problem

The σ_k -Yamabe problem:(J. Viaclovsky)

Given $[g]$, find $\tilde{g} \in [g]$ such that

$$\sigma_k(A_{\tilde{g}}) = \text{const.}$$

- When $k = 1$, this corresponds to the Yamabe problem.
- When $k \geq 2$ this equation fully nonlinear, and elliptic if

$$\mathcal{C}_k^+ = \{\tilde{g} \in [g] : \sigma_j(A_{\tilde{g}}) > 0, 1 \leq j \leq k\} \neq \emptyset$$

(or with A replaced by $-A$).

Existence theory for the σ_k -Yamabe problem

Existence theory for the σ_k -Yamabe problem

- \mathcal{C}^+ : Extensive (Chang-G-Yang, G-Viaclovsky, Y.Y. Li-A. Li, Han-Li, Sheng-Trudinger-Wang, Trudinger-Wang, Guan-Wang, Guan-Lin-Wang, Chen, etc.)

Existence theory for the σ_k -Yamabe problem

- \mathcal{C}^+ : Extensive (Chang-G-Yang, G-Viaclovsky, Y.Y. Li-A. Li, Han-Li, Sheng-Trudinger-Wang, Trudinger-Wang, Guan-Wang, Guan-Lin-Wang, Chen, etc.) In particular: when $n = 4$ and $k = 2$, existence proved by Chang-G-Yang.

Existence theory for the σ_k -Yamabe problem

- \mathcal{C}^+ : Extensive (Chang-G-Yang, G-Viaclovsky, Y.Y. Li-A. Li, Han-Li, Sheng-Trudinger-Wang, Trudinger-Wang, Guan-Wang, Guan-Lin-Wang, Chen, etc.) In particular: when $n = 4$ and $k = 2$, existence proved by Chang-G-Yang.
- \mathcal{C}^- :

Existence theory for the σ_k -Yamabe problem

- \mathcal{C}^+ : Extensive (Chang-G-Yang, G-Viaclovsky, Y.Y. Li-A. Li, Han-Li, Sheng-Trudinger-Wang, Trudinger-Wang, Guan-Wang, Guan-Lin-Wang, Chen, etc.) In particular: when $n = 4$ and $k = 2$, existence proved by Chang-G-Yang.
- \mathcal{C}^- : Once $k \geq 2$, essentially nothing...

Existence theory for the σ_k -Yamabe problem

- \mathcal{C}^+ : Extensive (Chang-G-Yang, G-Viaclovsky, Y.Y. Li-A. Li, Han-Li, Sheng-Trudinger-Wang, Trudinger-Wang, Guan-Wang, Guan-Lin-Wang, Chen, etc.) In particular: when $n = 4$ and $k = 2$, existence proved by Chang-G-Yang.
- \mathcal{C}^- : Once $k \geq 2$, essentially nothing... Viaclovsky: C^0 , C^1 -estimates for solutions; Sheng-Trudinger-Wang: Counterexample to (local) C^2 -estimates. Also, when $k = n$, connection to optimal transport.

Existence theory for the σ_k -Yamabe problem

- \mathcal{C}^+ : Extensive (Chang-G-Yang, G-Viaclovsky, Y.Y. Li-A. Li, Han-Li, Sheng-Trudinger-Wang, Trudinger-Wang, Guan-Wang, Guan-Lin-Wang, Chen, etc.) In particular: when $n = 4$ and $k = 2$, existence proved by Chang-G-Yang.
- \mathcal{C}^- : Once $k \geq 2$, essentially nothing... Viaclovsky: C^0, C^1 -estimates for solutions; Sheng-Trudinger-Wang: Counterexample to (local) C^2 -estimates. Also, when $k = n$, connection to optimal transport.
- Non-uniqueness for solutions of the Yamabe problem is well known; Schoen constructed explicit examples on $S^n \times S^1$. Viaclovsky generalized Schoen's construction to the fully nonlinear Yamabe problem when $k < n/2$.

The functional

Back to $n = 4$.

The functional

Back to $n = 4$.

Question: What corresponds to the Liouville energy?

The functional

Back to $n = 4$.

Question: What corresponds to the Liouville energy?

- Define

$$F_{CY}[u] = \int \left\{ 2\Delta u |\nabla u|^2 - |\nabla u|^4 - 2\text{Ric}(\nabla u, \nabla u) + R|\nabla u|^2 - 8u\sigma_2(A_g) \right\} dV_g - 2 \left(\int \sigma_2(A_g) dV \right) \log \left(\int e^{-4u} dV \right).$$

This formula is due to Branson-Orsted/Chang-Yang.

The functional

- u is a critical point of $F_{CY} \Leftrightarrow$ the conformal metric $g_u = e^{-2u}g$ satisfies
$$\sigma_2(A_u) \equiv \text{const.}$$

The functional

- u is a critical point of $F_{CY} \Leftrightarrow$ the conformal metric $g_u = e^{-2u}g$ satisfies

$$\sigma_2(A_u) \equiv \text{const.}$$

- F_{CY} can be expressed as a linear combination of regularized determinants.

The functional

- u is a critical point of $F_{CY} \Leftrightarrow$ the conformal metric $g_u = e^{-2u}g$ satisfies

$$\sigma_2(A_u) \equiv \text{const.}$$

- F_{CY} can be expressed as a linear combination of regularized determinants.
- When $(M, g) = (S^4, g_{S^4})$, Chang-Yang showed that $F|_{\mathcal{C}^+} \geq 0$, with equality given precisely by the image of the round metric under the conformal group.

Geodesics

- As in the case of surfaces, many of the geometric properties of the space $(\mathcal{C}^+, \langle \cdot, \cdot \rangle)$ depend on the existence/regularity of geodesics.

- As in the case of surfaces, many of the geometric properties of the space $(\mathcal{C}^+, \langle \cdot, \cdot \rangle)$ depend on the existence/regularity of geodesics.
- A path $u : [0, 1] \rightarrow \mathcal{C}^+$ is a geodesic \Leftrightarrow

$$u_{tt} = \frac{(-A_u + \sigma_1(A_u)g_u)(\nabla u_t, \nabla u_t)}{\sigma_2(A_u)}.$$

- As in the case of surfaces, many of the geometric properties of the space $(\mathcal{C}^+, \langle \cdot, \cdot \rangle)$ depend on the existence/regularity of geodesics.
- A path $u : [0, 1] \rightarrow \mathcal{C}^+$ is a geodesic \Leftrightarrow

$$u_{tt} = \frac{(-A_u + \sigma_1(A_u)g_u)(\nabla u_t, \nabla u_t)}{\sigma_2(A_u)}.$$

There is a more convenient way to write this:

- As in the case of surfaces, many of the geometric properties of the space $(\mathcal{C}^+, \langle \cdot, \cdot \rangle)$ depend on the existence/regularity of geodesics.
- A path $u : [0, 1] \rightarrow \mathcal{C}^+$ is a geodesic \Leftrightarrow

$$u_{tt} = \frac{(-A_u + \sigma_1(A_u)g_u)(\nabla u_t, \nabla u_t)}{\sigma_2(A_u)}.$$

There is a more convenient way to write this: let

$$E_u = u_{tt}A_u - \nabla u_t \otimes \nabla u_t,$$

then the geodesic equation can be written

$$\sigma_2(E_u) = 0.$$

- This is a degenerate elliptic, fully nonlinear equation. We regularize by letting

$$E_u^\epsilon = (1 + \epsilon)u_{tt}A_u - \nabla u_t \otimes \nabla u_t,$$

and for $f > 0$, solve

$$\sigma_2(E_u^\epsilon) = fu_{tt}.$$

- This is a degenerate elliptic, fully nonlinear equation. We regularize by letting

$$E_u^\epsilon = (1 + \epsilon)u_{tt}A_u - \nabla u_t \otimes \nabla u_t,$$

and for $f > 0$, solve

$$\sigma_2(E_u^\epsilon) = fu_{tt}.$$

- Unlike the surface case, estimates for the regularized geodesic equation degenerate at the C^2 -level:

- This is a degenerate elliptic, fully nonlinear equation. We regularize by letting

$$E_u^\epsilon = (1 + \epsilon)u_{tt}A_u - \nabla u_t \otimes \nabla u_t,$$

and for $f > 0$, solve

$$\sigma_2(E_u^\epsilon) = fu_{tt}.$$

- Unlike the surface case, estimates for the regularized geodesic equation degenerate at the C^2 -level: given endpoints $u_0, u_1 \in \mathcal{C}^+$ and $\epsilon > 0$, we can prove the existence of a solution of the regularized equation connecting u_0 and u_1 with

$$|u_\epsilon| + |(u_\epsilon)_t| + |\nabla u_\epsilon| + \epsilon\{|\nabla^2 u_\epsilon| + |(u_\epsilon)_{tt}| + |\nabla(u_\epsilon)_t|\} \leq C.$$

Main Results

Theorem 1

$(\mathcal{C}^+, \langle \cdot, \cdot \rangle)$ has non-positive sectional curvature.

Main Results

Theorem 1

$(\mathcal{C}^+, \langle \cdot, \cdot \rangle)$ has non-positive sectional curvature.

Theorem 2

The functional F_{CY} is geodesically convex.

Main Results

Theorem 1

$(\mathcal{C}^+, \langle \cdot, \cdot \rangle)$ has non-positive sectional curvature.

Theorem 2

The functional F_{CY} is geodesically convex.

- The proof of Theorem 2 also depends on a version of Andrews' inequality, but in a very non-obvious way.

Main Results, cont.

The most surprising result:

The most surprising result:

Theorem 3

If $\mathcal{C}^+ \neq \emptyset$ and (M, g) is not conformally equivalent to the sphere, then there is a **unique** metric $\tilde{g} \in \mathcal{C}^+$ which minimizes F_{CY} , and is therefore a solution of

$$\sigma_2(A_{\tilde{g}}) \equiv \frac{3}{2}.$$

The most surprising result:

Theorem 3

If $\mathcal{C}^+ \neq \emptyset$ and (M, g) is not conformally equivalent to the sphere, then there is a **unique** metric $\tilde{g} \in \mathcal{C}^+$ which minimizes F_{CY} , and is therefore a solution of

$$\sigma_2(A_{\tilde{g}}) \equiv \frac{3}{2}.$$

Also,

$$(i) \quad \text{Vol}(\tilde{g}) < \text{Vol}(S^4),$$

The most surprising result:

Theorem 3

If $\mathcal{C}^+ \neq \emptyset$ and (M, g) is not conformally equivalent to the sphere, then there is a **unique** metric $\tilde{g} \in \mathcal{C}^+$ which minimizes F_{CY} , and is therefore a solution of

$$\sigma_2(A_{\tilde{g}}) \equiv \frac{3}{2}.$$

Also,

$$(i) \quad \text{Vol}(\tilde{g}) < \text{Vol}(S^4),$$

and

$$(ii) \quad 0 < \text{Ric}(\tilde{g}) < \frac{1}{2}R_{\tilde{g}}\tilde{g}.$$

Some Remarks about Theorem 3

- The gap between $Vol(\tilde{g})$ and the volume of the round sphere is an interesting (conformal) invariant. In some cases it can be (sharply) estimated:

Some Remarks about Theorem 3

- The gap between $Vol(\tilde{g})$ and the volume of the round sphere is an interesting (conformal) invariant. In some cases it can be (sharply) estimated:

◇ (Poon, '86): If $M = \mathbb{C}\mathbb{P}^2$, then $Vol(\tilde{g}) \leq 2\pi^2$, with equality iff $\tilde{g} = g_{FS}$.

Some Remarks about Theorem 3

- The gap between $Vol(\tilde{g})$ and the volume of the round sphere is an interesting (conformal) invariant. In some cases it can be (sharply) estimated:

◇ (Poon, '86): If $M = \mathbb{CP}^2$, then $Vol(\tilde{g}) \leq 2\pi^2$, with equality iff $\tilde{g} = g_{FS}$.

◇ (G - '98): If $b^+ > 0$, then $Vol(\tilde{g}) \leq \frac{2}{9}\pi^2(2\chi(M) + 3\tau(M))$, with equality iff \tilde{g} is K-E.

Some Remarks about Theorem 3

- The gap between $Vol(\tilde{g})$ and the volume of the round sphere is an interesting (conformal) invariant. In some cases it can be (sharply) estimated:

◇ (Poon, '86): If $M = \mathbb{C}\mathbb{P}^2$, then $Vol(\tilde{g}) \leq 2\pi^2$, with equality iff $\tilde{g} = g_{FS}$.

◇ (G - '98): If $b^+ > 0$, then $Vol(\tilde{g}) \leq \frac{2}{9}\pi^2(2\chi(M) + 3\tau(M))$, with equality iff \tilde{g} is K-E.

The proof of Theorem 3, cont.

- The uniqueness claim of Theorem 3 would follow from Theorem 2 (geodesic convexity of F_{CY}) if we could connect any two metrics in \mathcal{C}^+ by a sufficiently regular geodesic.

The proof of Theorem 3, cont.

- The uniqueness claim of Theorem 3 would follow from Theorem 2 (geodesic convexity of F_{CY}) if we could connect any two metrics in \mathcal{C}^+ by a sufficiently regular geodesic. However, in view of our estimates above, as the regularizing parameter $\epsilon \rightarrow 0$, we lose C^2 -bounds.

The proof of Theorem 3, cont.

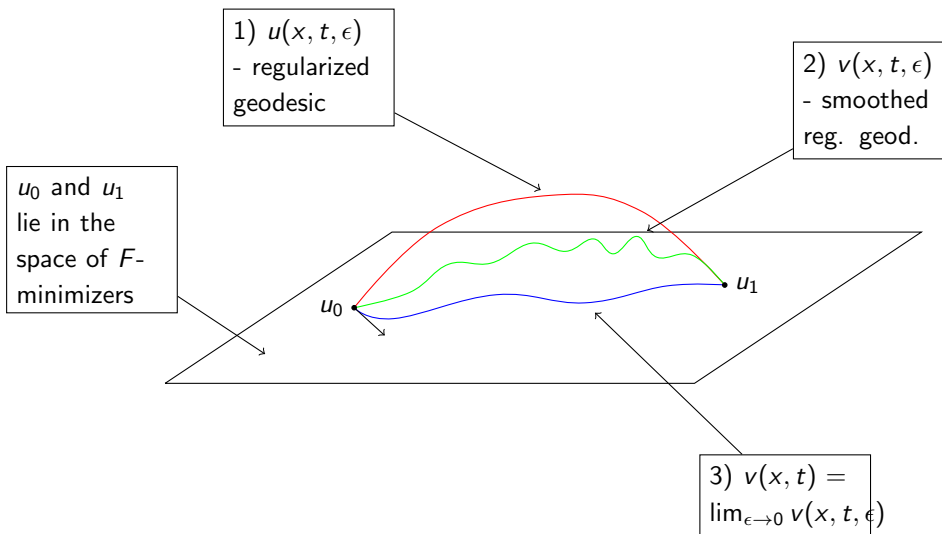
- The uniqueness claim of Theorem 3 would follow from Theorem 2 (geodesic convexity of F_{CY}) if we could connect any two metrics in \mathcal{C}^+ by a sufficiently regular geodesic. However, in view of our estimates above, as the regularizing parameter $\epsilon \rightarrow 0$, we lose C^2 -bounds.
- Consequently, we need to smooth the approximate geodesics, without changing the value of F_{CY} too much.

The proof of Theorem 3, cont.

- The uniqueness claim of Theorem 3 would follow from Theorem 2 (geodesic convexity of F_{CY}) if we could connect any two metrics in \mathcal{C}^+ by a sufficiently regular geodesic. However, in view of our estimates above, as the regularizing parameter $\epsilon \rightarrow 0$, we lose C^2 -bounds.
- Consequently, we need to smooth the approximate geodesics, without changing the value of F_{CY} too much.
- The idea is to use the flow introduced by Guan-Wang:

$$\frac{\partial u}{\partial t} = \log \sigma_2(A_u).$$

The Proof, in a Picture:



- In higher dimensions there are two ways to proceed. One way is to define

$$\langle \alpha, \beta \rangle_{g_u} = \int \alpha \beta \sigma_{n/2}(A_u) dV_u.$$

However, once the dimensions $n \geq 6$ one needs to impose an additional condition (local conformal flatness) in order to have a reasonable notion of the connection, geodesic, etc.

Dimension $n \geq 6$

- In higher dimensions there are two ways to proceed. One way is to define

$$\langle \alpha, \beta \rangle_{g_u} = \int \alpha \beta \sigma_{n/2}(A_u) dV_u.$$

However, once the dimensions $n \geq 6$ one needs to impose an additional condition (local conformal flatness) in order to have a reasonable notion of the connection, geodesic, etc.

- There is an alternate definition which has many nice formal properties, in which one replaces $\sigma_{n/2}(A_u)$ with the 'renormalized volume coefficient' (cf. Chang-Fang, Chang-Fang-Graham). The associated formulas become quite complicated, though.

Happy Birthday, et Bonne Anniversaire, Claude!