

# On Split Cuts from Elementary Disjunctions

Everything You Always Wanted to Know About BUT  
Were Afraid to Ask Egon

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Joint work with Matteo Fischetti & Andrea Tramontani

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## Notation & Assumptions

- We consider:

$$\min\{c^T x : Ax \geq b, x \text{ integer}\} \quad (1)$$

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- We are also **given** an **elementary disjunction** on the form  $x_j \leq \pi_0$  OR  $x_j \geq \pi_0 + 1$  such that  $x_j^* \in ]\pi_0, \pi_0 + 1[$ .



## Notation & Assumptions (cont.d)

- Such a cut can be separated by solving the so-called **Cut Generating Linear Program**:

$$\begin{aligned} \text{(CGLP)} \quad & \min \quad \gamma x^* - \gamma_0 \\ & \gamma \quad = \quad u^T A \quad - \quad u_0 e_j \\ & \gamma \quad = \quad v^T A \quad + \quad v_0 e_j \\ & \gamma_0 \quad = \quad u^T b \quad - \quad u_0 \pi_0 \\ & \gamma_0 \quad = \quad v^T b \quad + \quad v_0 (\pi_0 + 1) \\ & u, w, \quad v, z, \quad u_0, v_0 \quad \geq 0 \end{aligned}$$

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- The truncation of such a cone can be obtained in many different ways through a so-called **normalization** constraint and Balas, Ceria & Cornuéjols (1996) – **BCC** for short – used

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- Lately, Balas & Perregaard (2002) developed an elegant and efficient way of solving the CGLP **in the space of the original variables** which represents a crucial speed-up.

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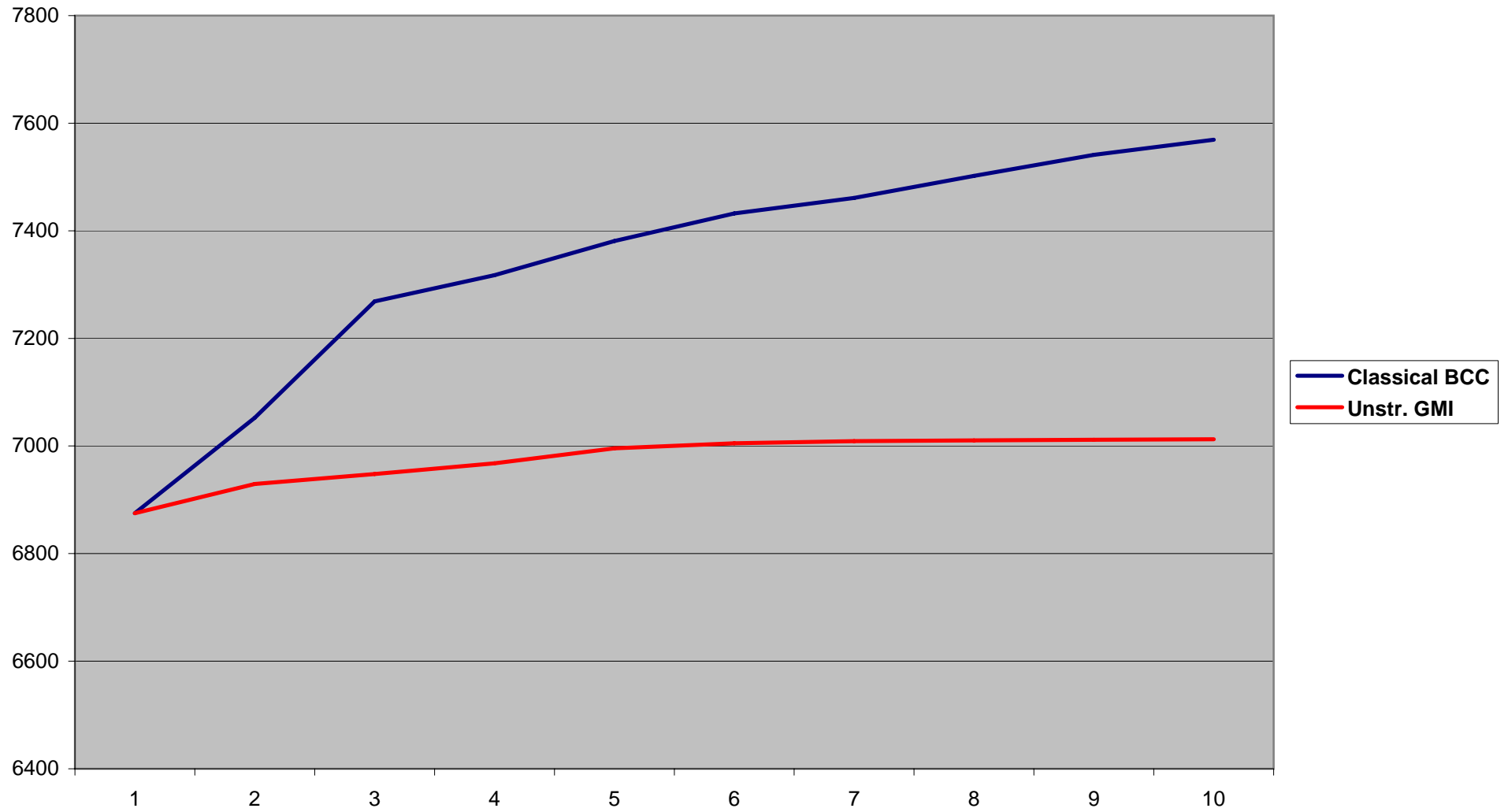
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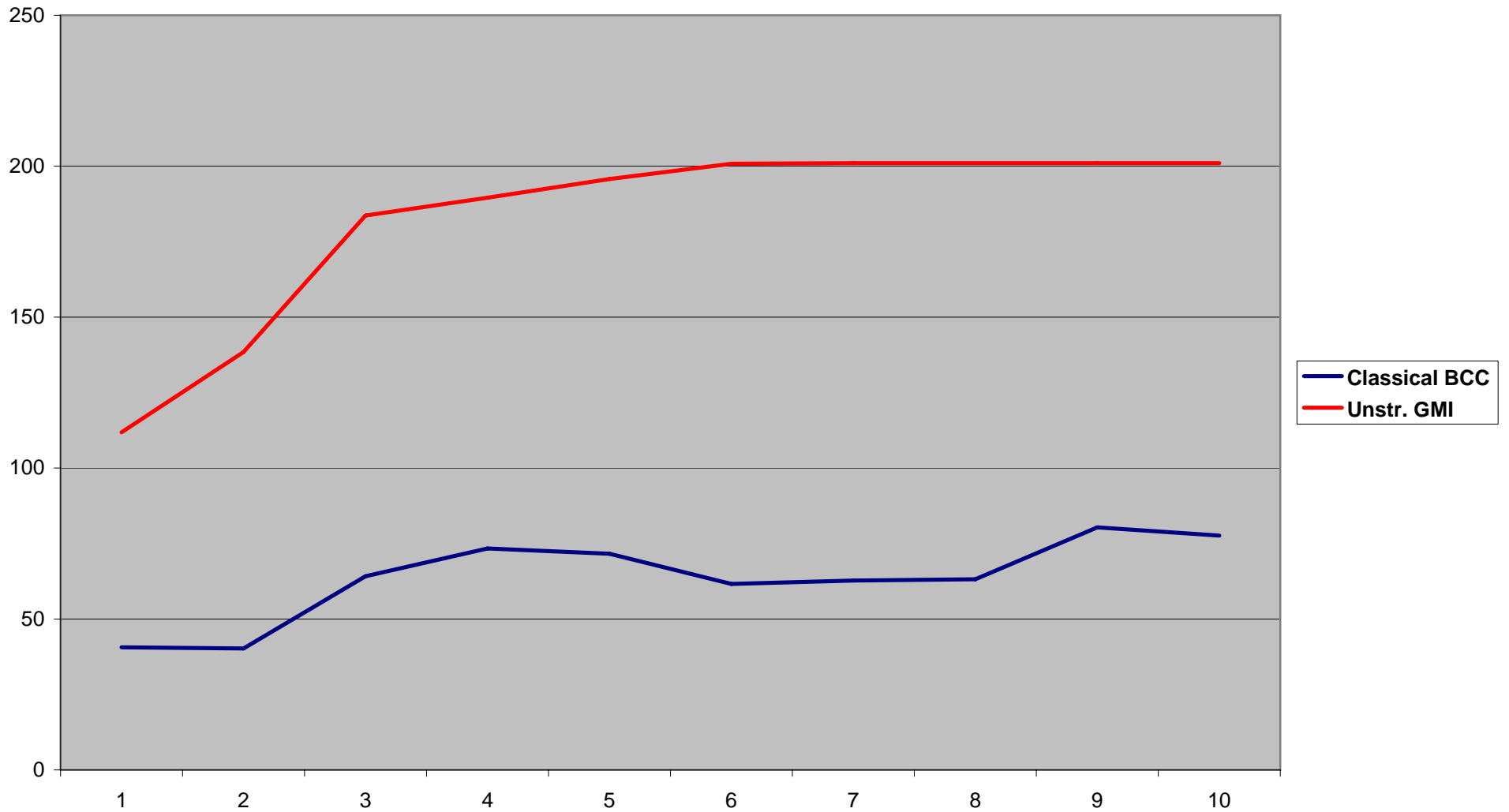
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- The **first set of experiments** we designed is intended at understanding how and how much one can really gain from such a strengthening and in order to do this we **avoided strengthening** the cuts *a posteriori* **through the Balas & Jeroslow** procedure.
- Within 10 rounds of cuts, the **indicators** we report are:
  1. **quality** of the lower bound
  2. average cuts' **density**
  3. cuts' **rank**
  4. average **cardinality of  $(u, v)$** , i.e., how many constraints used on average to generate a cut

# Instance p0201: lower bound

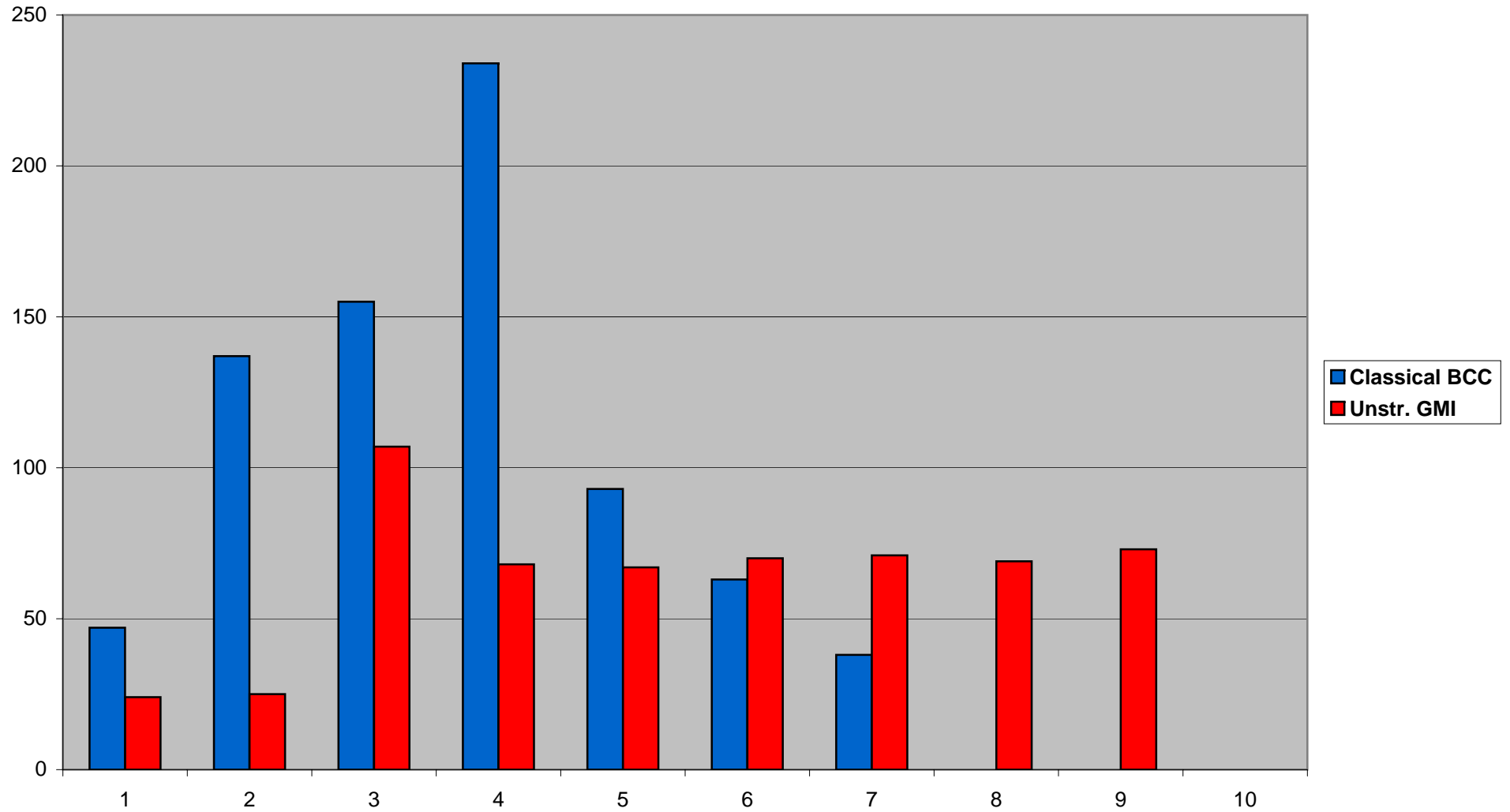


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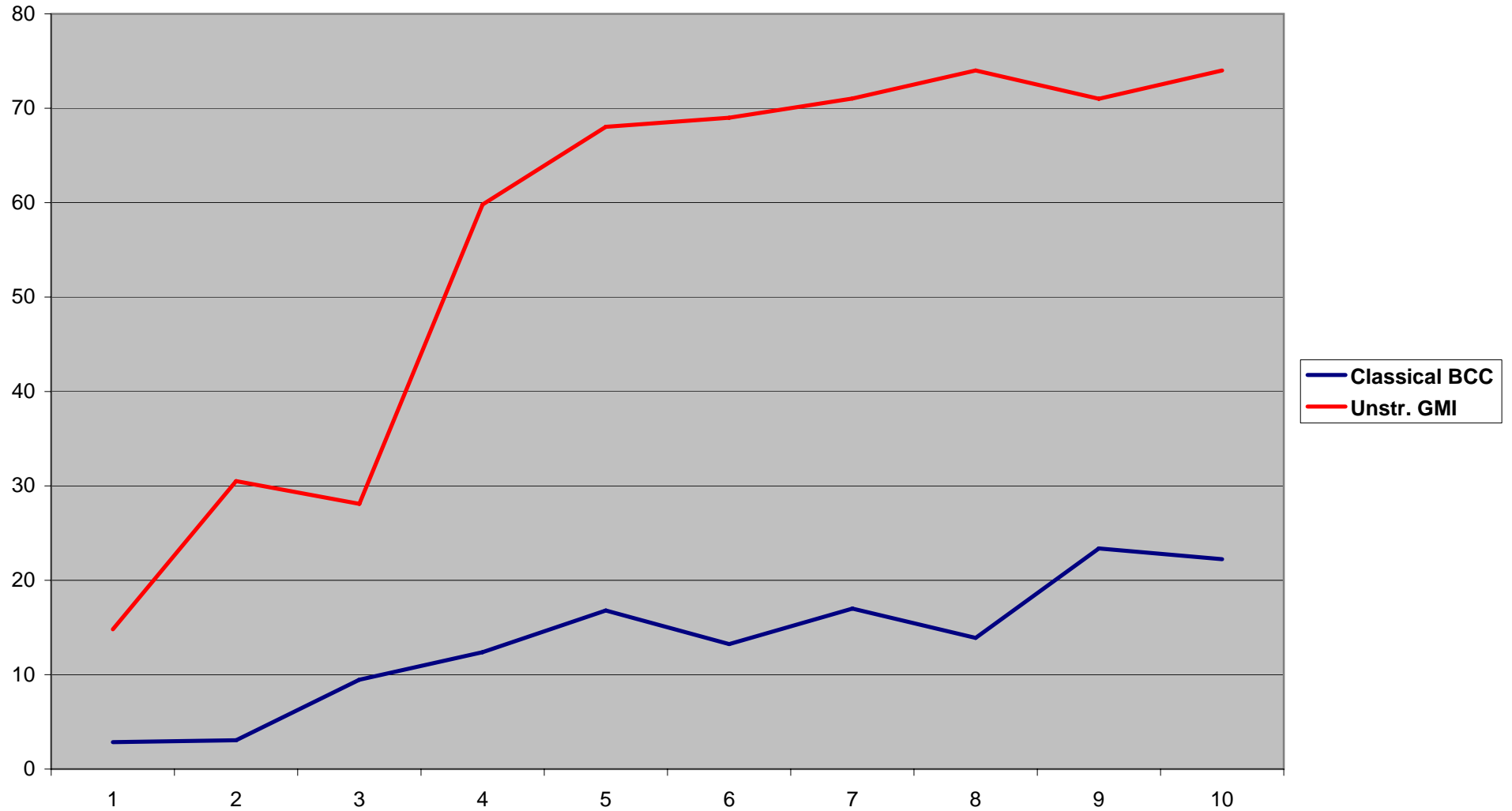




## Instance p0201: cuts' rank



## Instance p0201: average cardinality of $(u, v)$



## In Summary

Table 1: 10 iterations of cuts. At each iteration one cut is generated from any fractional variable. No strengthening in the cut computation.

Unstrengthened GMI vs. "Classical" BCC approach						
Instance	Unstrengthened GMI			"Classical" BCC		
	n.cuts	gap%	$\#(u, v)$	n.cuts	gap%	$\#(u, v)$
bell3a	137	70.74	59.49	71	70.74	43.72
bell5	202	28.18	31.20	178	94.29	11.75
blend2	156	28.73	11.70	192	30.51	8.10
flugpl	93	15.15	7.57	92	18.36	5.85
gt2	191	98.71	14.52	196	93.46	10.28
lseu	152	32.94	14.34	196	41.33	9.17
*m.share1	68	0.00	1.00	74	0.00	1.39
mod008	104	12.09	10.40	139	17.05	12.41
p0033	103	58.33	5.72	113	67.86	4.81
p0201	574	18.58	56.03	767	93.82	13.43
rout	445	8.52	135.39	434	24.26	68.07
*stein27	235	0.00	19.74	252	0.00	6.53
vpm1	255	36.95	9.03	263	55.84	5.39
vpm2	424	42.08	71.72	403	74.96	17.27

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avg.	236.333	<b>37.583</b>	35.593	253.667	<b>56.873</b>	17.521

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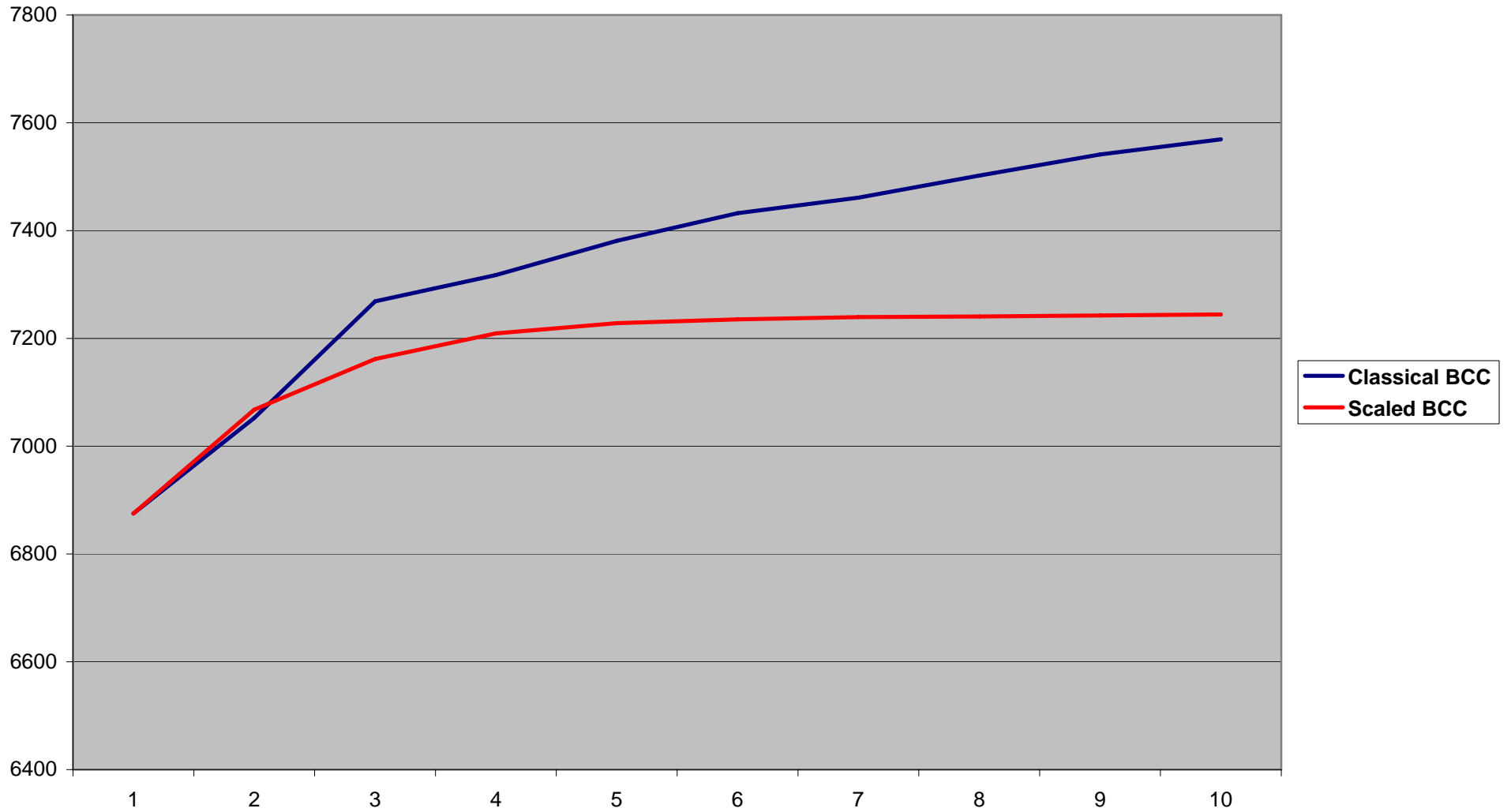
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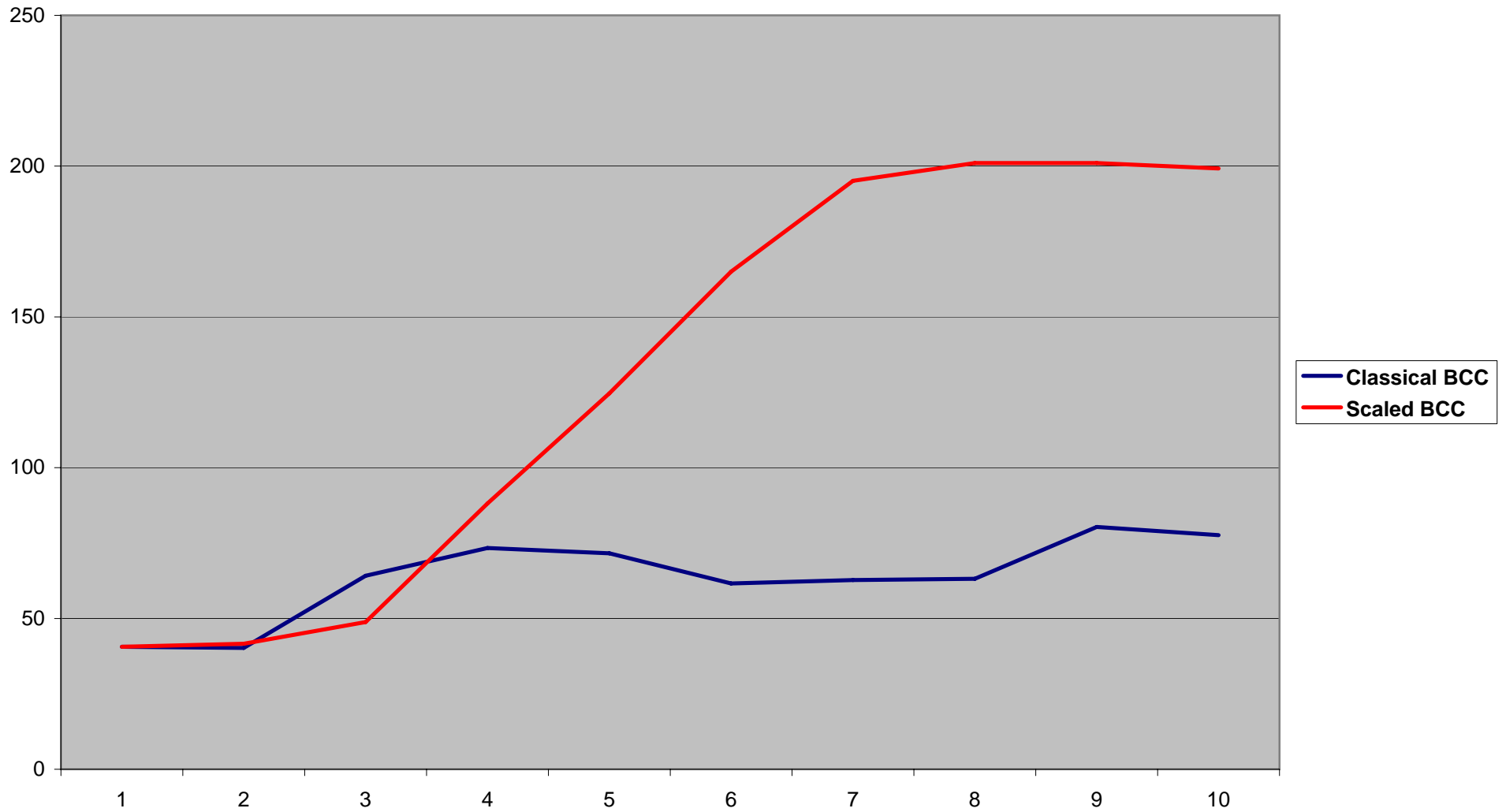
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- However, nothing is perfect! **Normalization (2) is dependent on the scaling of the constraints**. In the **second set of experiments** we simply multiplied by 1,000 any generated cut before adding it to the current relaxation.

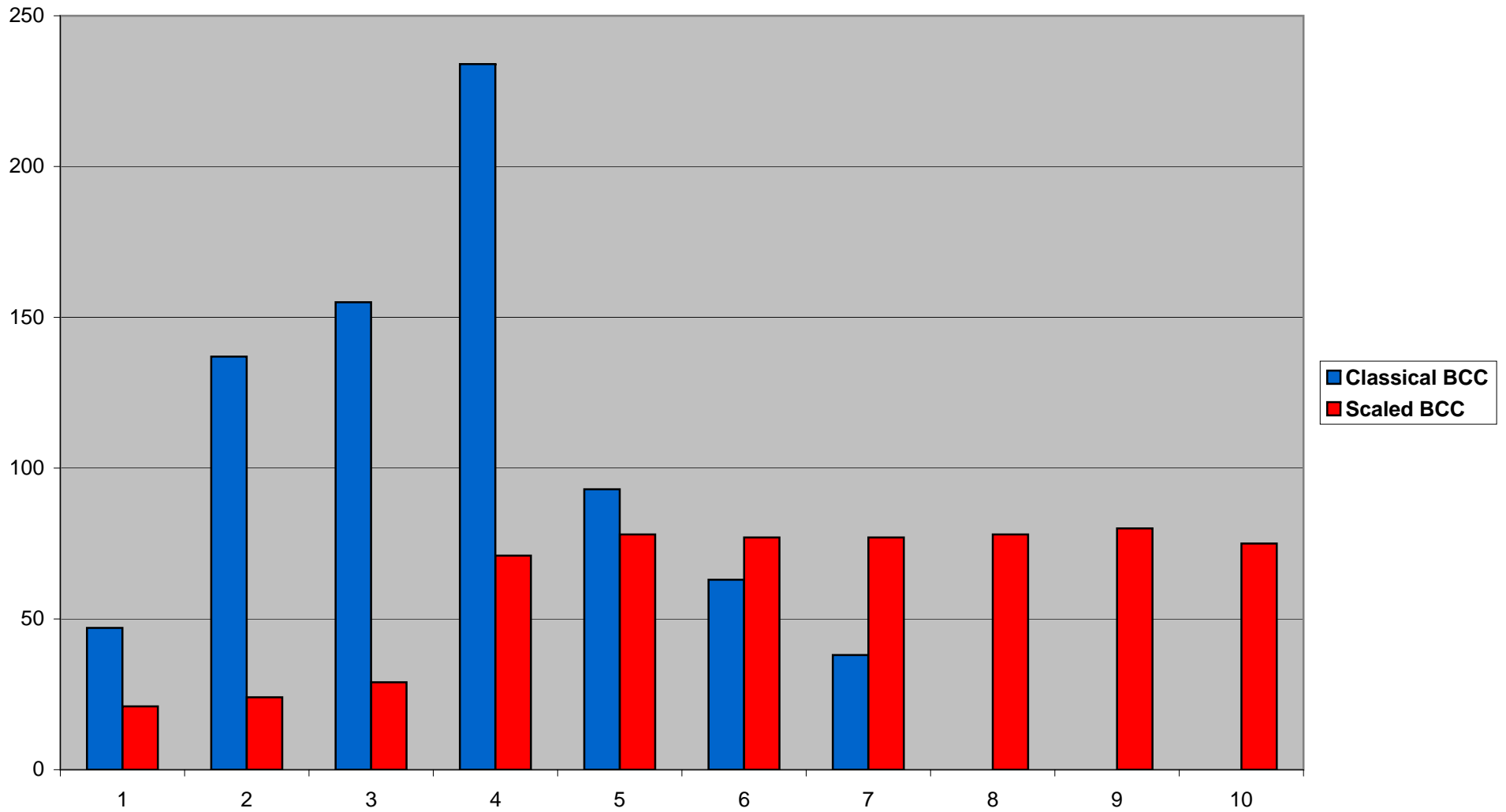
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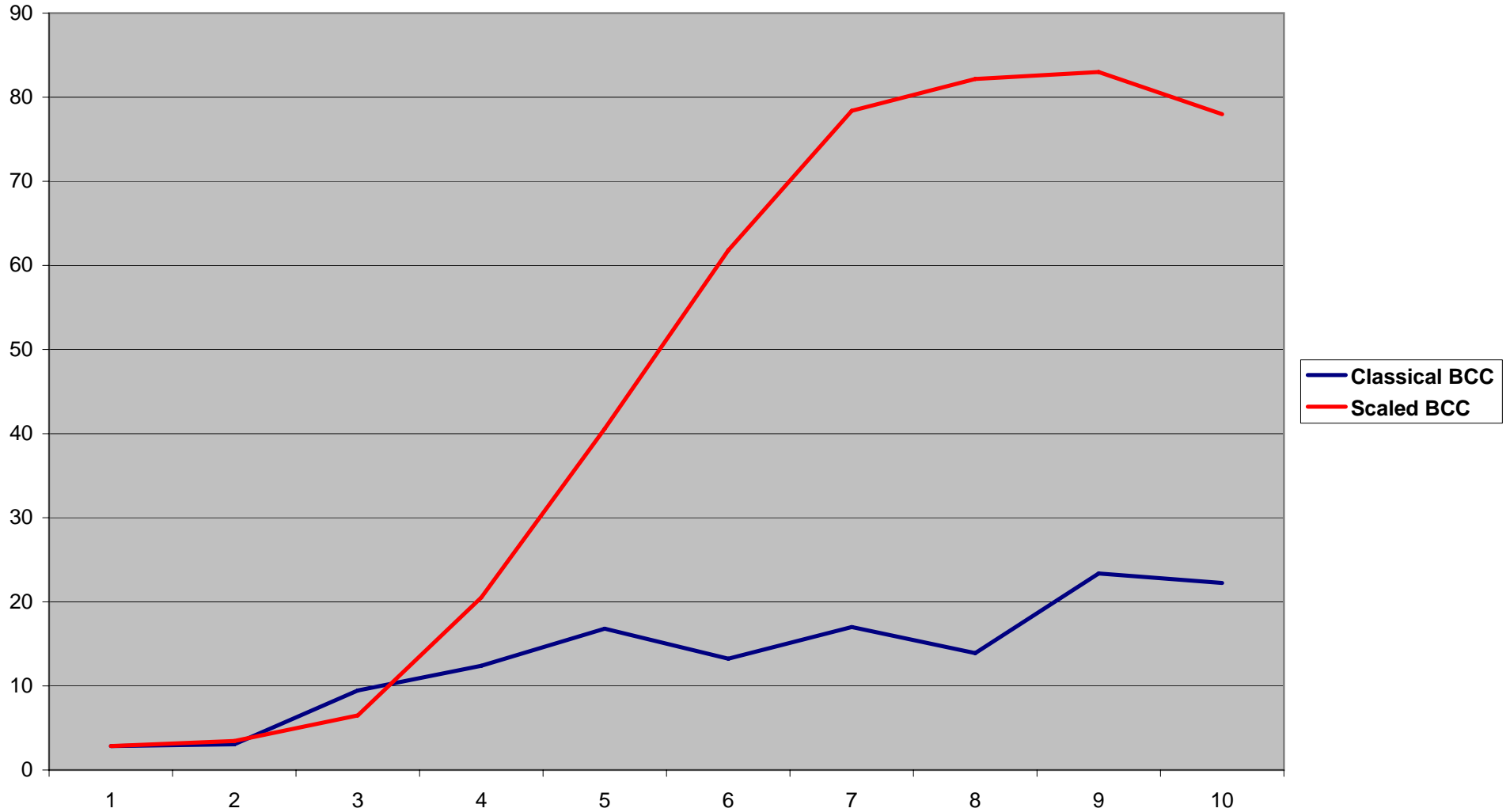


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lseu	196	41.33	9.17	137	38.58	10.88
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mod008	139	17.05	12.41	104	3.90	10.21
p0033	113	67.86	4.81	94	57.09	6.40
p0201	767	93.82	13.43	610	49.91	45.72
rout	434	24.26	68.07	435	13.03	152.66
*stein27	252	0.00	6.53	248	0.00	22.39
vpm1	263	55.84	5.39	244	47.59	8.50
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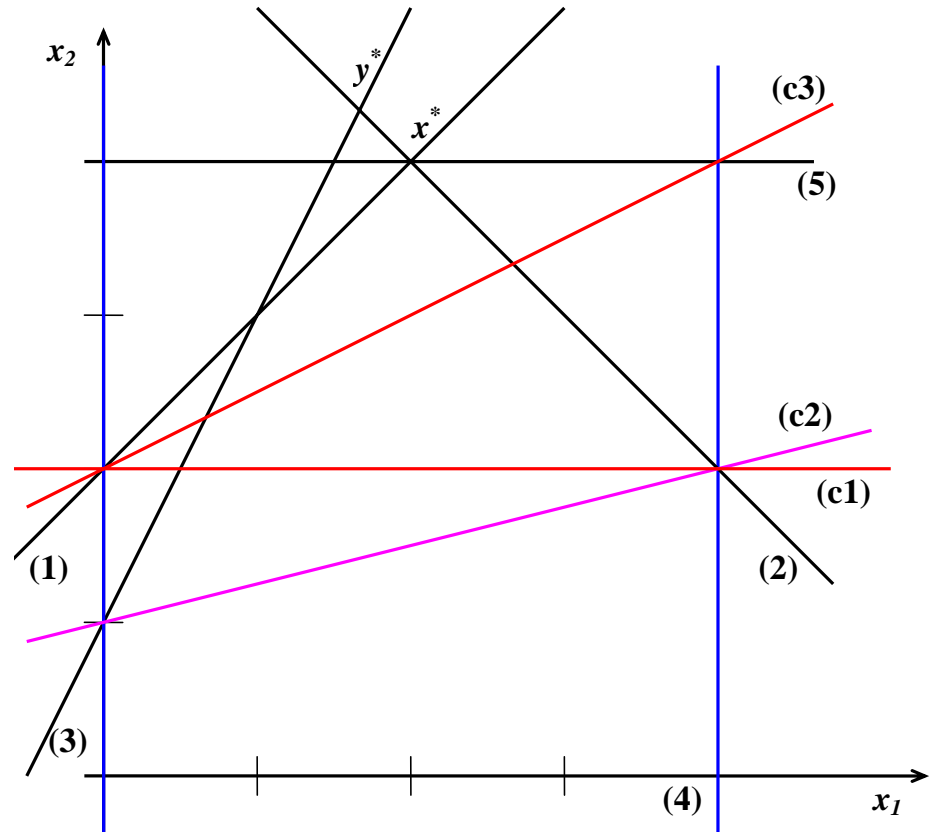
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## Nothing is perfect: Example 1

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 \min & -x_1 & -2x_2 & \\
 (1) & 4x_1 & -4x_2 & \geq -2 \\
 (2) & -2x_1 & -2x_2 & \geq -3 \\
 (3) & 8x_1 & -4x_2 & \geq -1 \\
 (4) & -x_1 & & \geq -1 \\
 (5) & & -k x_2 & \geq -k \quad (k > 0) \\
 & x_1, & x_2 & \geq 0
 \end{array}$$

Cuts from the disjunction  $x_1 \leq 0$  OR  $x_1 \geq 1$ :

$$\begin{array}{llll}
 (c1) & & 2x_2 & \leq 1 \\
 (c2) & -x_1 & +4x_2 & \leq 1 \\
 (c3) & -x_1 & +2x_2 & \leq 1
 \end{array}$$



(c1) : corresponds to the basic solution of the CGLP  $(u_1, v_2, u_0, v_0)$ , of value  $z_1 = -\frac{2}{11}$ , optimal for  $k \leq 8$

(c2) : corresponds to the basic solution of the CGLP  $(u_3, v_2, u_0, v_0)$ , of value  $z_2 = -\frac{1}{6}$ , never optimal

(c3) : corresponds to the basic solution of the CGLP  $(u_1, v_5, u_0, v_0)$ , of value  $z_3 = -\frac{k}{4+5k}$ , optimal for  $k \geq 8$

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  4. in other words, working on the extended space  $(\gamma, \gamma_0, u, v, u_0, v_0)$  makes points in the interior of the polyhedron become vertices but this is independent of the normalization itself.

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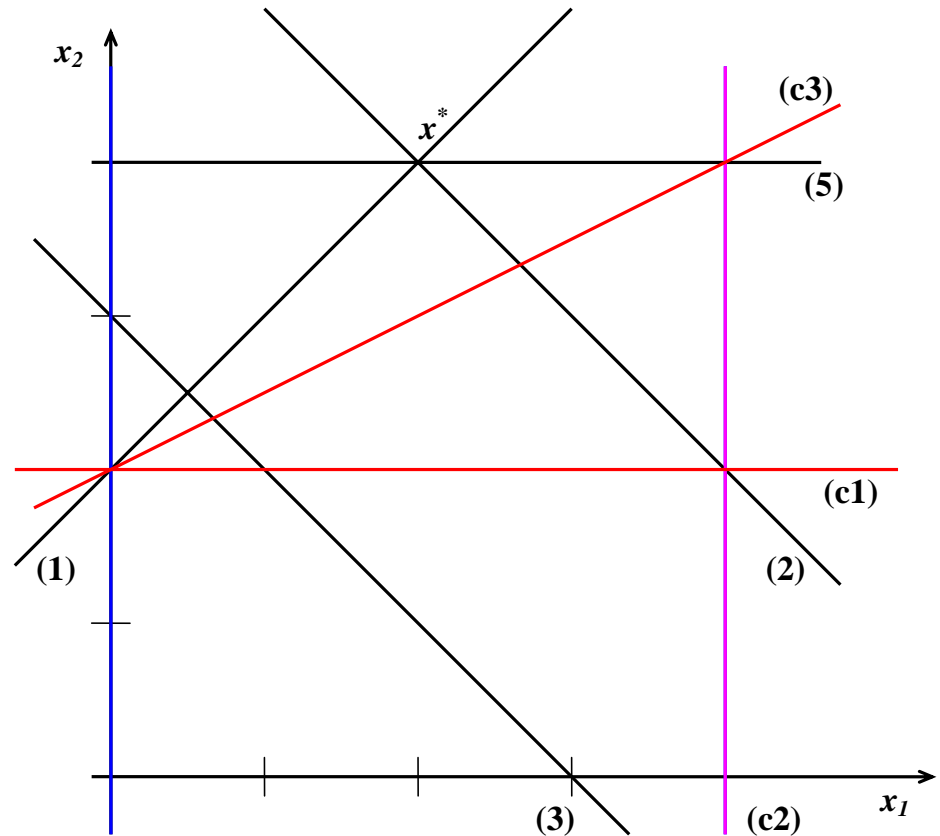
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  4. in other words, working on the extended space  $(\gamma, \gamma_0, u, v, u_0, v_0)$  makes points in the interior of the polyhedron become vertices but this is independent of the normalization itself.
  5. however, the normalization changes the ranking of these vertices in terms of violation and this can result in very bad choices in terms of separated cuts.

## Nothing is perfect: Example 2

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 (1) & 2x_1 & -2x_2 & \geq -1 \\
 (2) & -2x_1 & -2x_2 & \geq -3 \\
 (3) & 4x_1 & +4x_2 & \geq 3 \\
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- (c1) : corresponds to the basic solution of the CGLP  $(u_1, v_2, u_0, v_0)$ , of value  $z_1 = -\frac{1}{6}$
- (c2) : corresponds to the basic solution of the CGLP  $(u_1, u_3, u_0, v_0)$ , of value  $z_2 = -\frac{1}{22}$
- (c3) : corresponds to the basic solution of the CGLP  $(u_1, v_5, u_0, v_0)$ , of value  $z_3 = -\frac{1}{10}$

$P_0 = \emptyset \Rightarrow x_1 \geq 1$  is a valid cut, but is not the best one for the CGLP

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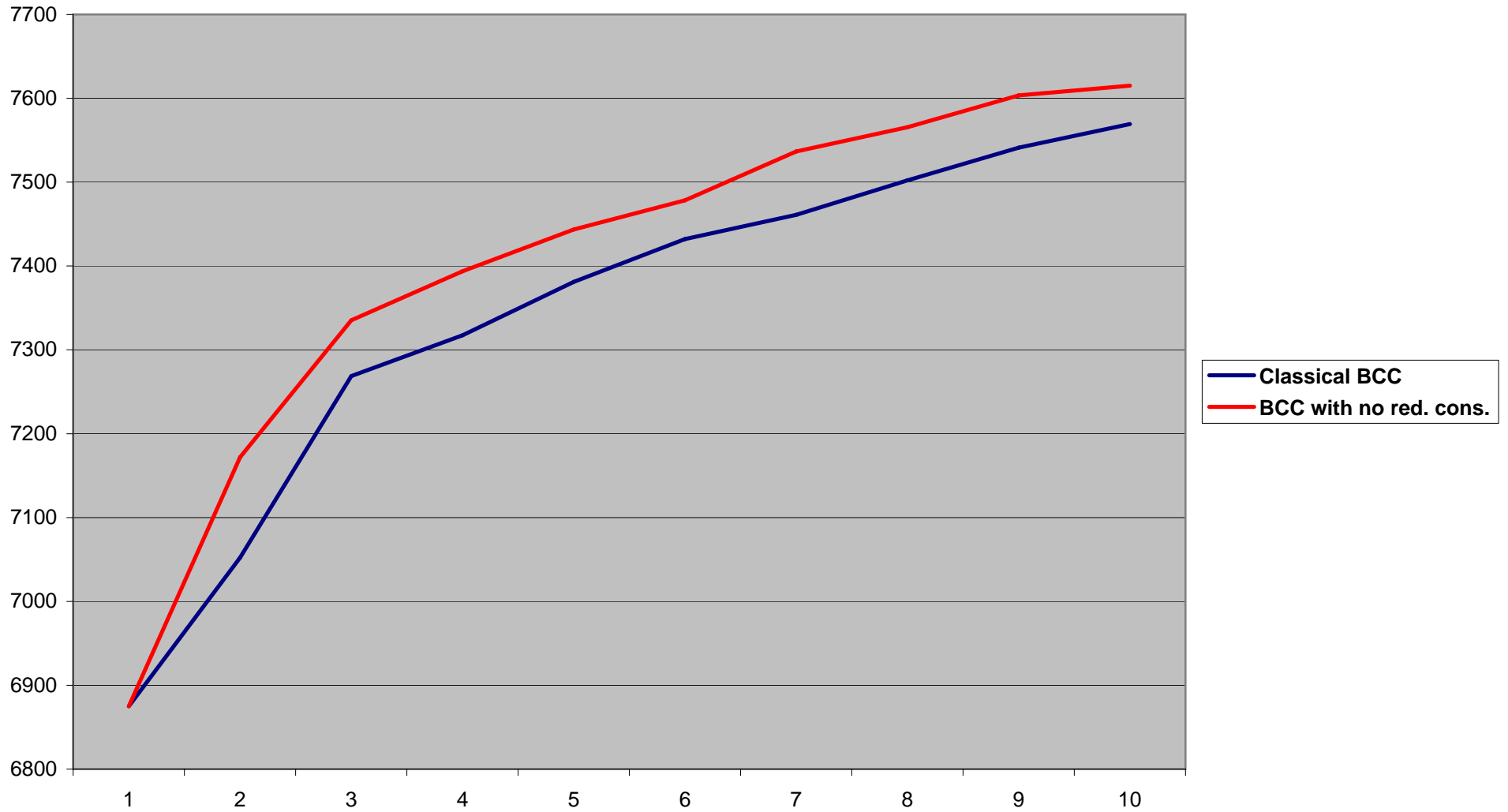
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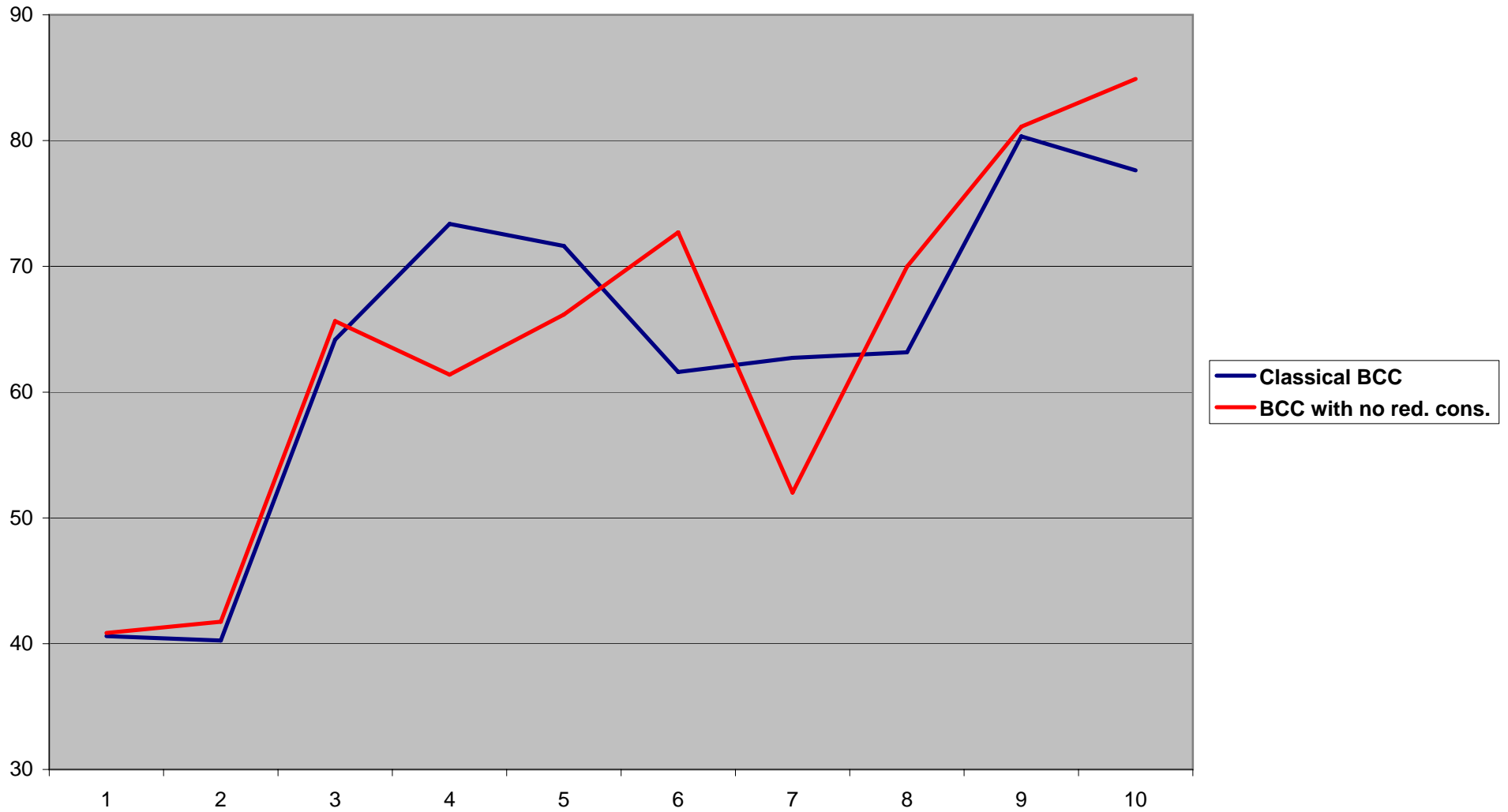
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- In the third set of experiments we eliminated redundant constraints in a trivial way (i.e., by solving LPs) before solving the CGLP. To get a full picture, we did not project the separation problem on the support of  $x^*$  (to be discussed later).

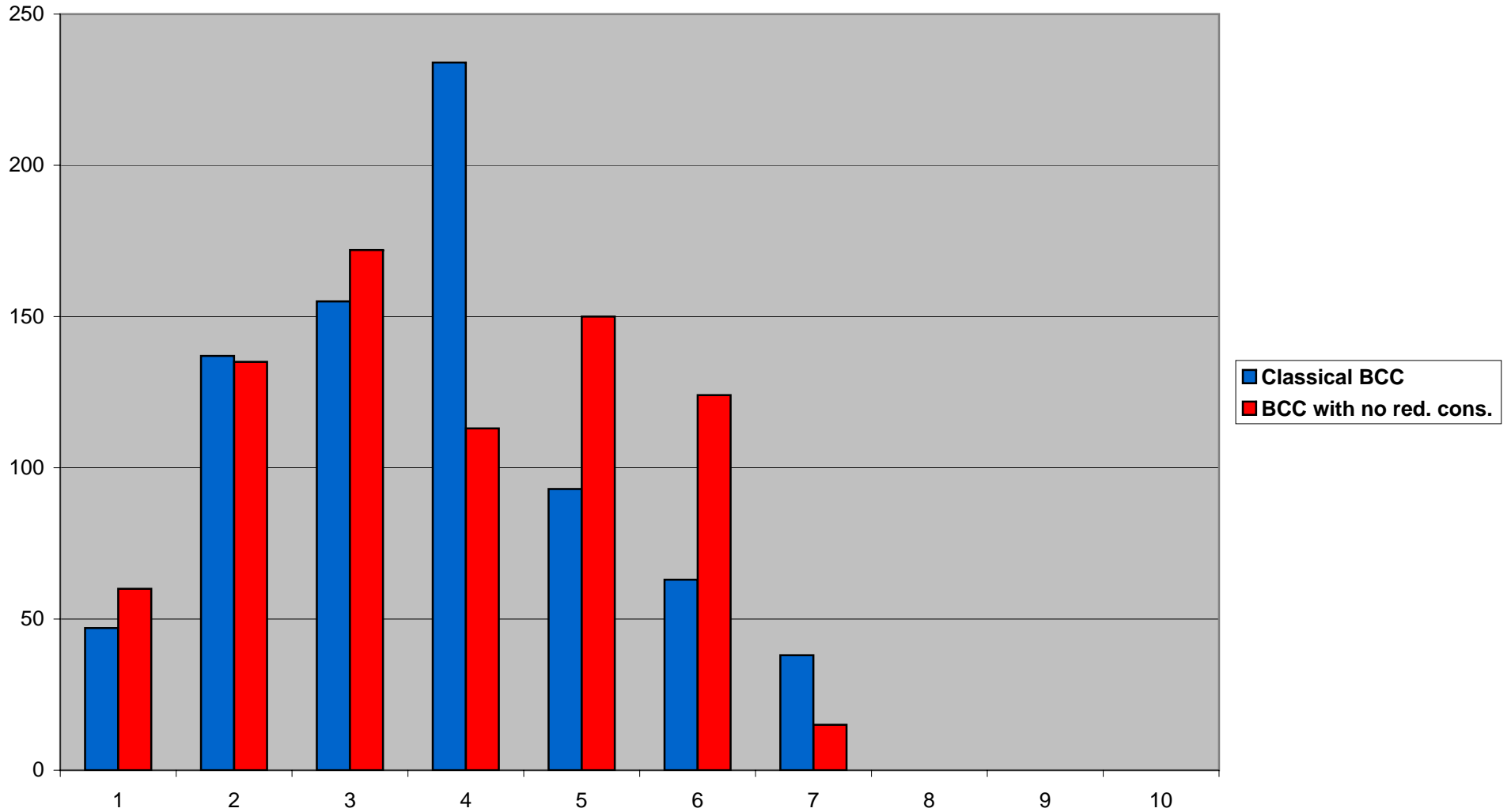
# Instance p0201: lower bound



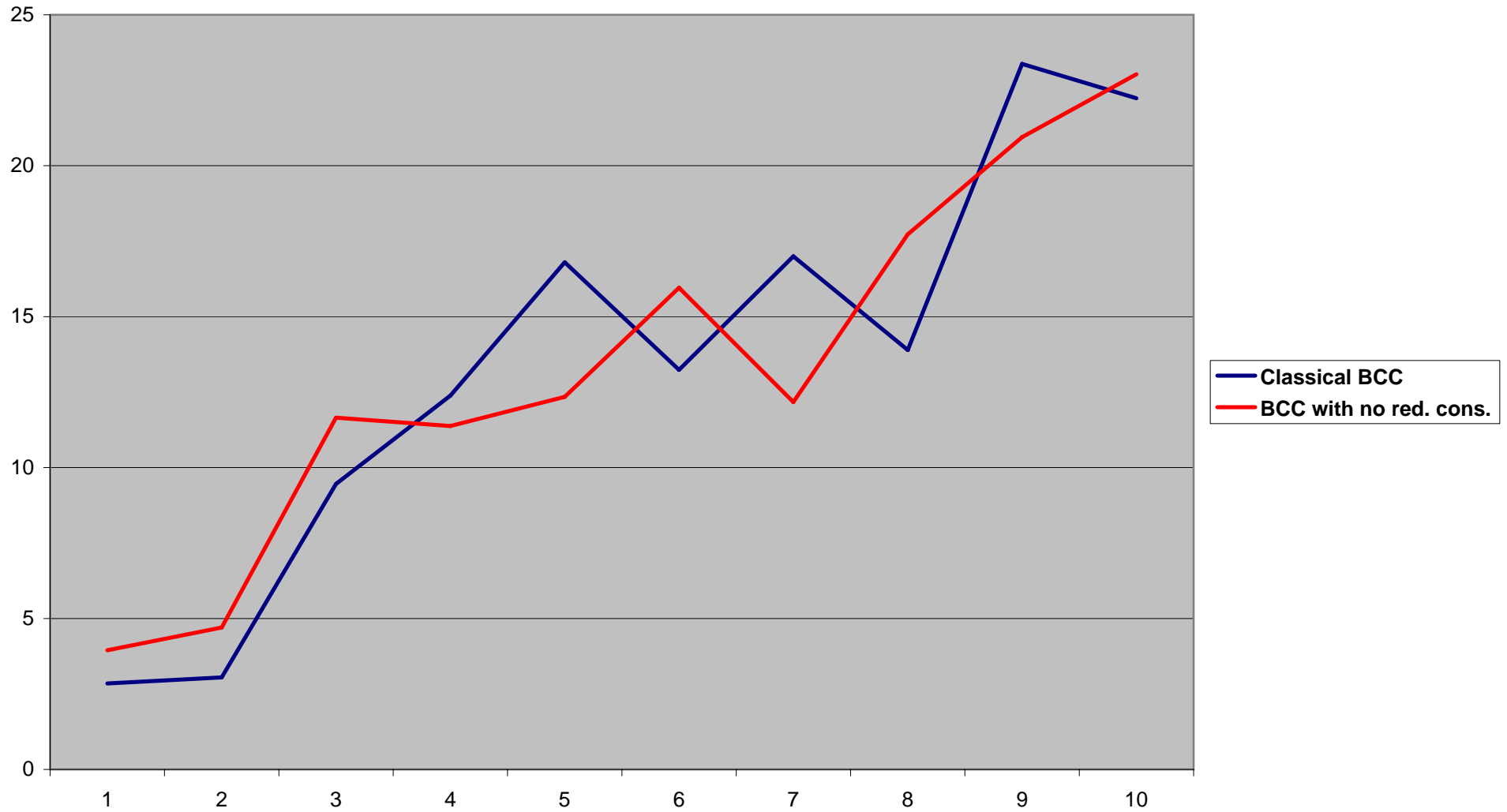
## Instance p0201: average cuts' density



## Instance p0201: cuts' rank



## Instance p0201: average cardinality of $(u, v)$



## In Summary

Table 3: 10 iterations of cuts. At each iteration one cut is generated from any fractional variable. No strengthening in the cut computation.

“Classical” BCC approach vs. “No redundancy” BCC approach with no projection						
Instance	“Classical” BCC			“No redundancy” BCC		
	n.cuts	gap%	$\#(u, v)$	n.cuts	gap%	$\#(u, v)$
bell3a	71	70.74	64.65	54	70.74	66.19
bell5	188	94.12	16.83	189	93.54	15.80
blend2	197	30.49	71.42	212	30.63	119.90
flugpl	93	18.34	6.45	90	18.83	6.48
gt2	218	94.13	58.11	167	93.68	63.16
lseu	171	42.46	23.86	184	45.10	30.96
*m.share1	77	0.00	55.99	77	0.00	56.00
mod008	107	15.46	304.18	107	15.48	304.19
p0033	116	57.25	8.75	126	70.32	10.99
p0201	692	92.53	23.40	757	98.31	37.44
rout	349	29.46	189.07	384	31.93	202.18
*stein27	251	0.00	7.29	249	0.00	6.46
vpm1	267	50.62	11.13	282	54.55	11.10
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avg.	238.250	55.861	66.840	244.000	58.298	74.267

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- In other words, not stating explicitly (4), i.e., **projecting, implies allowing the use of the constraint**  $x_k \geq 0$  in the separation of the cut which can be a very bad idea.
- This seems to be **particularly crucial for the variable bounds** and we defined an **extended support** of  $x^*$  by avoiding projecting out variables at the bound whose bound constraints are in turn redundant.

## Working on the support: computation

Table 4: 10 iterations of cuts. At each iteration one cut is generated from any fractional variable. No strengthening in the cut computation.

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blend2	192	30.51	53.06	8.10	200	30.99	53.54	10.84	193	30.53	53.99	8.34
flugpl	92	18.36	86.11	5.85	93	18.94	86.11	5.89	93	18.86	86.29	5.95
gt2	196	93.46	18.30	10.28	191	94.13	18.14	10.58	187	93.88	20.00	13.10
lseu	196	41.33	29.44	9.17	191	40.16	27.08	12.28	178	43.45	29.41	9.08
*m.share1	74	0.00	11.94	1.39	130	0.00	13.39	2.56	77	0.00	12.59	1.69
mod008	139	17.05	4.51	12.41	136	17.70	4.42	12.17	157	19.13	5.85	14.43
p0033	113	67.86	55.76	4.81	106	70.32	55.76	5.74	146	70.29	58.84	5.89
p0201	767	93.82	45.02	13.43	873	81.59	43.43	25.83	769	100.00	48.93	13.39
rout	434	24.26	42.19	68.07	355	6.56	38.11	58.23	353	30.88	69.46	140.29
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vpm1	263	55.84	62.14	5.39	275	50.18	62.25	6.30	259	57.63	65.18	6.60
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avg.	253.667	56.873	50.268	17.521	257.667	54.269	49.677	18.675	245.167	58.793	53.529	24.281



## Conclusions and Future Work

- We got some **insights about** the use of **normalizations** in the separation of disjunctive cuts.
- We have shown that such **normalizations** – even the good ones – are **not fully safe**.
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- We have shown that such **normalizations** – even the good ones – are **not fully safe**.
- We have shown that **redundant constraints hurt** in the separation of disjunctive cuts.
- Even after the elimination of redundant constraints one might separate non supporting cuts.  
Can we do better?
- Can we come up with a better normalization (equivalently, a different objective function) such that the **cheating effect of redundant constraints can be mitigated**?
- Can we **remove redundant constraints efficiently**, e.g., in the framework of Balas & Perregaard?
- Can we separate **directly on the  $(\gamma, \gamma_0)$  space**?